



U.S. Department of Transportation  
Federal Highway Administration

Turner-Fairbank  
Highway Research Center

SAXTON  
LABORATORY

# MAP Creation Tool Progress Update

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# Agenda



- ▶ Project overview.
- ▶ Compiler updates.
- ▶ Base map investigation.
- ▶ Questions?



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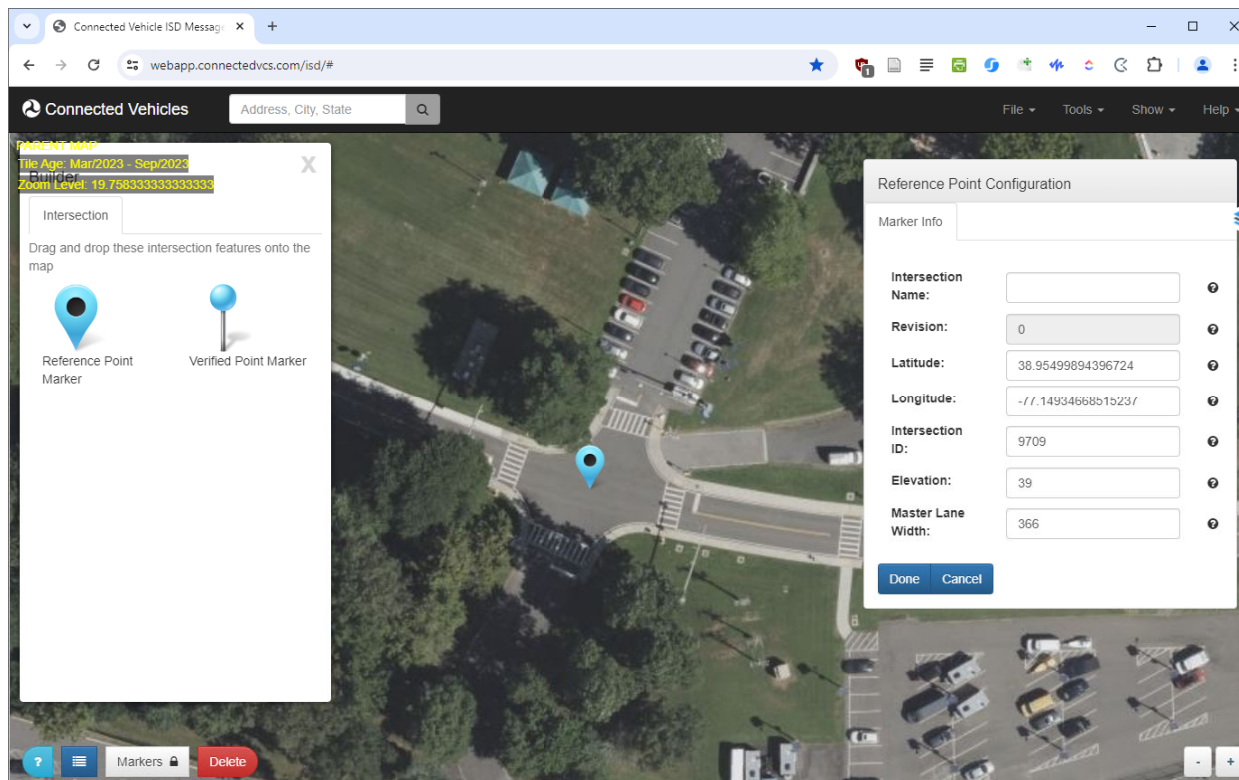
# Project Overview

# Overview



- ▶ The current version of the MAP creation tool is widely used and in high demand:<sup>(1)</sup>
  - ▷ Complies with existing SAE International® J2735™ MAP standard.<sup>(2)</sup>
  - ▷ Relies on a proprietary Abstract Syntax Notation One (ASN.1) compiler.<sup>(3)</sup>
- ▶ This project will reassess the existing MAP tool and add capabilities based on input from stakeholders:<sup>(1)</sup>
  - ▷ Eliminate dependence on the proprietary ASN.1 compiler.<sup>(3)</sup>
  - ▷ Include support for the J2945/A message, currently in development.<sup>(4)</sup>
  - ▷ Address stakeholder comments regarding the existing MAP tool.<sup>(1)</sup>
  - ▷ Create a community of practice.

# USDOT MAP Tool



Source: FHWA.<sup>(1)</sup>

# Speed Limits



### Reference Point Configuration

Marker Info | Intersection Info

Layer ID:  ⓘ

---

Speed Limit Type:  ⌵ ✖ ⓘ

Velocity:  ⓘ

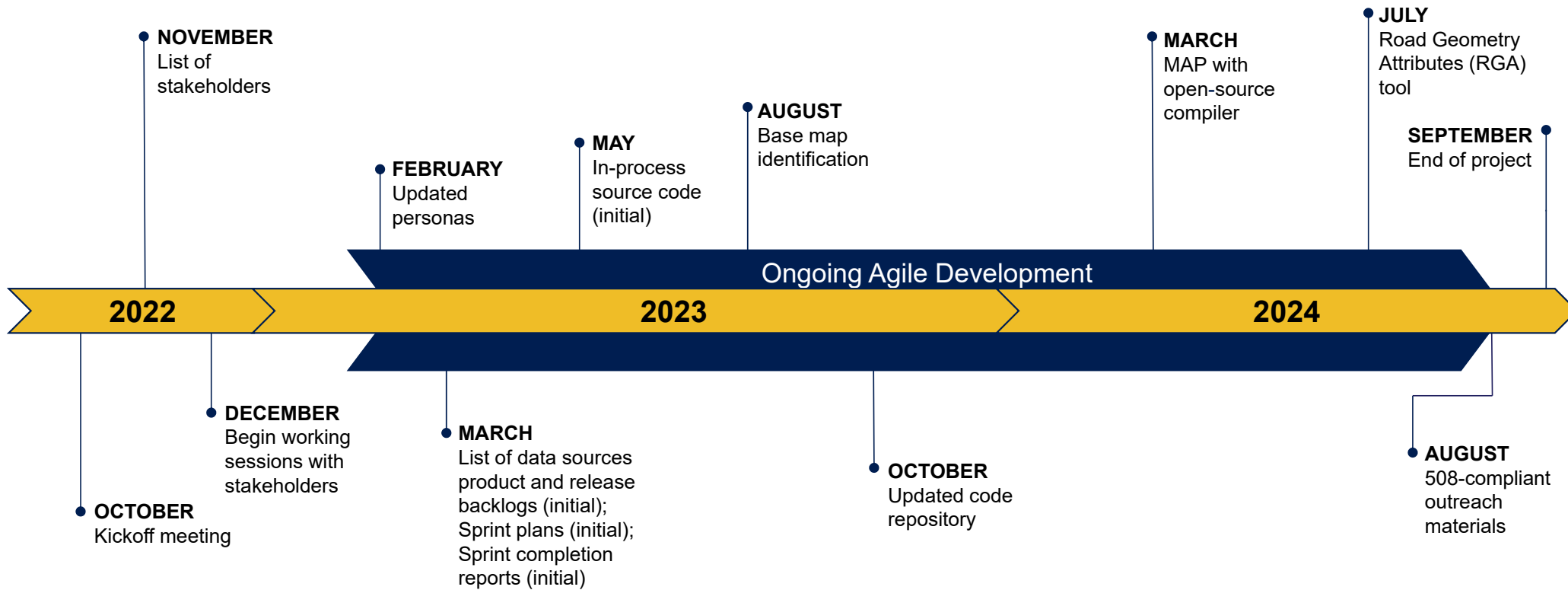
Add Row +

Done Cancel

Can set for an intersection if you make a parent map, then a child map

Source: FHWA.<sup>(1)</sup>

# Timeline



Source: FHWA.



# Phases of Work



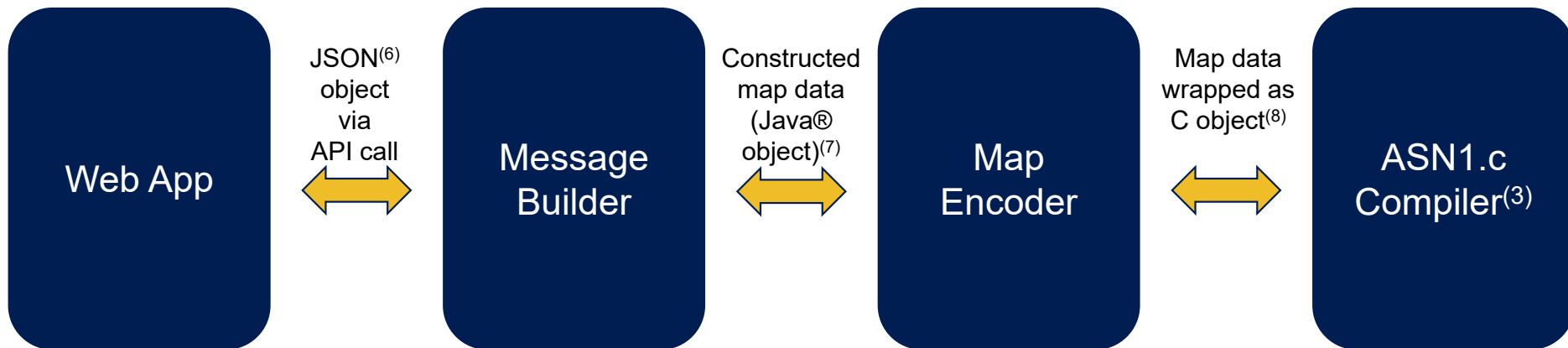
- ▶ Integrate an open-source compiler:
  - ▷ Identification of ASN.1c compiler.<sup>(3)</sup>
  - ▷ Integration of ASN.1c compiler into the existing MAP tool.<sup>(3,1)</sup>
  - ▷ Testing of open-source compiler.
  
- ▶ Revisit the base map:
  - ▷ Currently supplied by Bing.<sup>(5)</sup>
  - ▷ Four alternatives evaluated.
  
- ▶ Develop support for RGA message: creation of requirements based on the draft standard.<sup>(4)</sup>



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# Compiler Updates

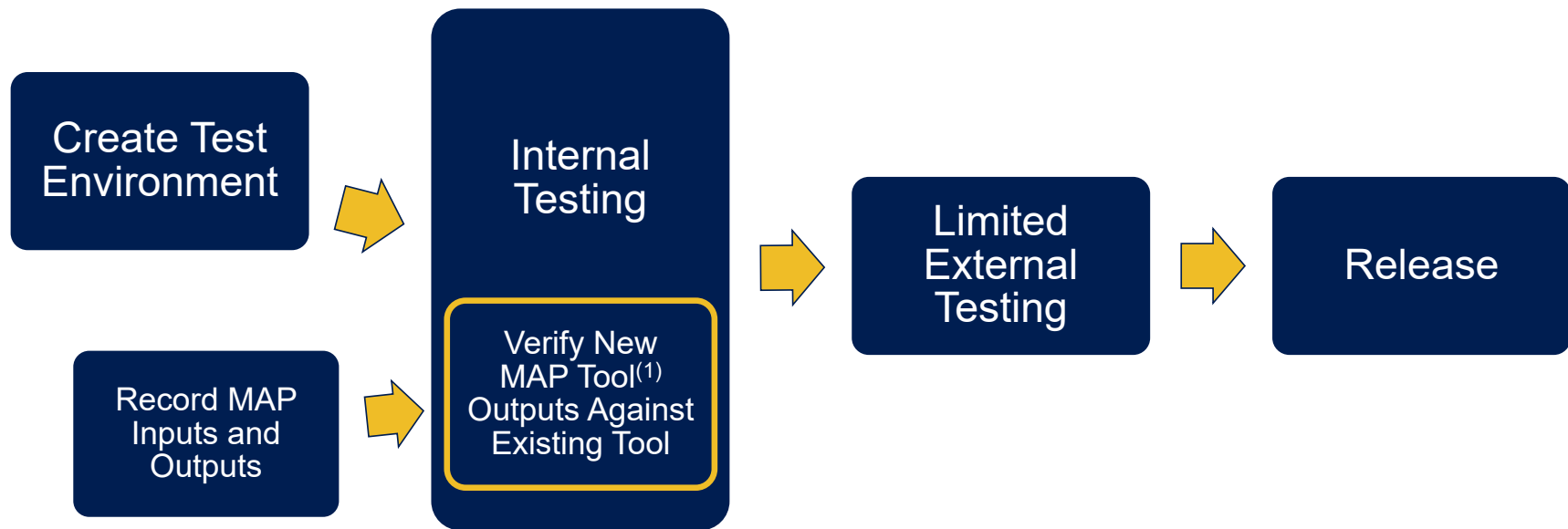
# MAP Tool ASN1.c Architecture (1,3)



API = application programming interface.

Source: FHWA.

# MAP Tool Open-Source Compiler Testing<sup>(1)</sup>



Source: FHWA.



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# Base Map Investigation

# Base Map Investigation Data



Map Source	U.S. Satellite Map Sources	Web Interface/API	Lat/Lon Decimal Places	Altitude Available	Items Used To Compute Precision (m/pixel)			Datum	Projection	Satellite Imagery Year
					Pixels per Tile (N <sup>2</sup> ) (N)	Max Zoom Level	Max Resolution (m/pixel)			
→ Google® Earth™ <sup>(9)</sup> and engine (satellite, not 3D imagery)	NASA, USGS, Landsat 8, and many other sources	Web interface	7	Yes	N/A	~23	~0.027	WGS 84 <sup>(12)</sup>	N/A	Accessible, varies by region
		API	7+							
Google Maps® platform <sup>(13)</sup>	AirBus™, NASA, TerraMetrics™, USGS, Maxar™, and USDA/FPAC/GEO	Web interface	6	Yes	256	21	0.075	WGS 84 <sup>(12)</sup>	Mercator	Accessible, varies by region
		API	7+							
→ Azure® Maps™ <sup>(11)</sup>	TomTom® and AirBus; unable to identify others	API/SDK only	7+	Yes	256	24	0.009	WGS 84 <sup>(12)</sup>	Mercator	Not accessible
Bing Maps™ <sup>(5)</sup>	TomTom, Vexcel™ Imaging, Earthstar Geographics SIO, and Maxar	Web interface	6	Yes	256	20	0.149	WGS 84 <sup>(12)</sup>	Mercator	Not easily accessible
		API/SDK only	7+							
→ Mapbox™ <sup>(10)</sup>	NASA MODIS, satellites, Maxar, Nearmap™, and other open and proprietary sources	API/SDK only	7+	Yes	512	22	0.019	WGS 84 <sup>(12)</sup>	Default is Mercator; other options are available	Not accessible

API = application programming interface; FPAC = Farm Production and Conservation; GEO = Group on Earth Observations; Lat = latitude; Lon = longitude; Max = maximum; N = number of pixels; N/A = not applicable; NASA = National Aeronautics and Space Administration; N<sup>2</sup> = number of pixels, squared; SDK = software development kit; SIO = Scripps Institution of Oceanography; 3D = three-dimensional; USDA = U.S. Department of Agriculture; USGS = U.S. Geological Survey; WGS = World Geodetic System.

Source: FHWA.

# Base Map Investigation Data



Map Source	U.S. Satellite Map Sources	Web Interface/API	Lat/Lon Decimal Places	Altitude Available	Items Used To Compute Precision (m/pixel)			Datum	Projection	Satellite Imagery Year
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Google Maps <sup>®</sup> platform <sup>(13)</sup>	AirBus <sup>™</sup> , NASA, TerraMetrics <sup>™</sup> , USGS, Maxar <sup>™</sup> , and USDA/FPAC/GEO	Web interface	6	Yes	256	21	0.075	WGS 84 <sup>(12)</sup>	Mercator	Accessible, varies by region
		API	7+							
Azure <sup>®</sup> Maps <sup>™(11)</sup>	TomTom <sup>®</sup> and AirBus; unable to identify others	API/SDK only	7+	Yes	256	24	0.009	WGS 84 <sup>(12)</sup>	Mercator	Not accessible
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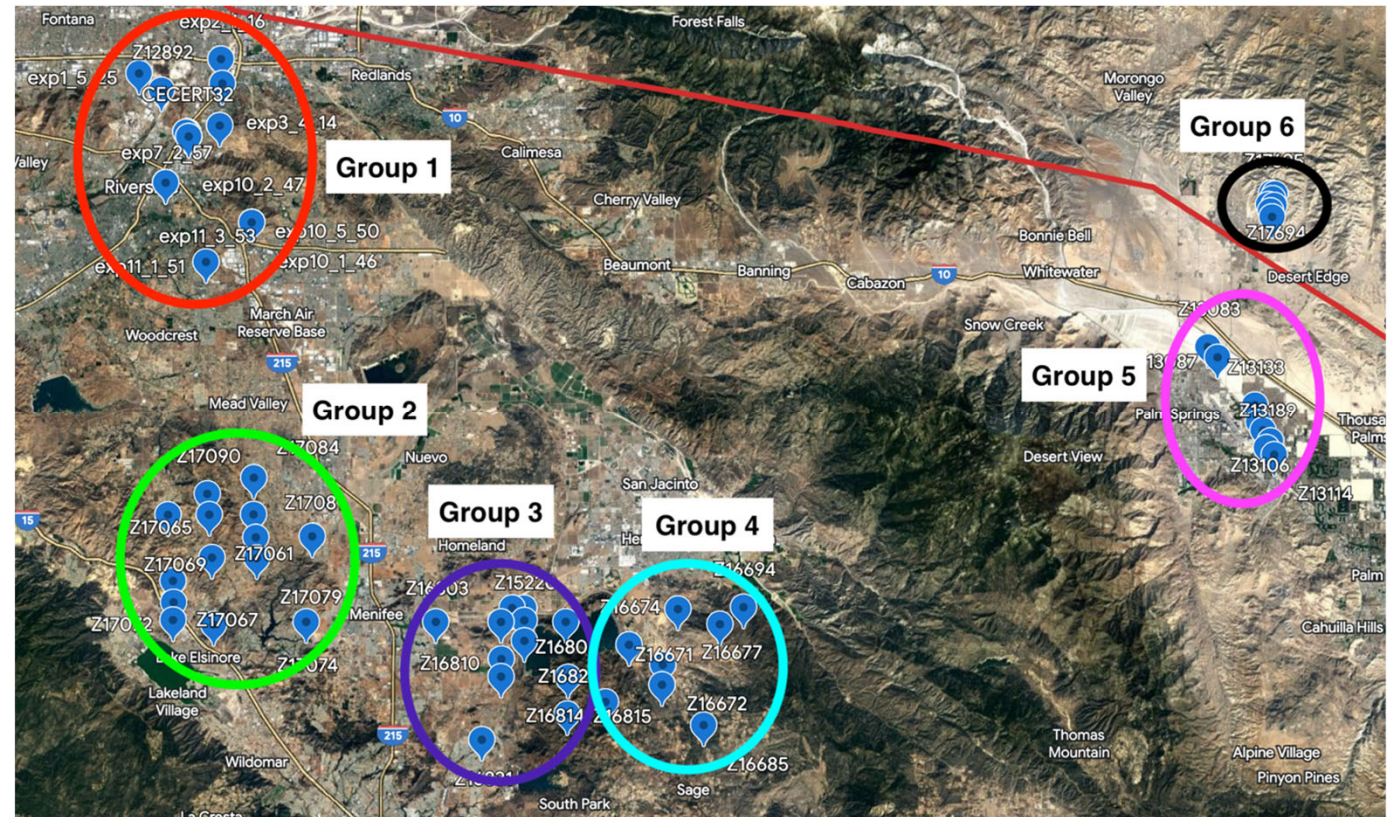
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Source: FHWA.

# Base Map Evaluation



- ▶ Evaluation used points surveyed by the University of California, Riverside, and the Riverside Flood Control District.
- ▶ Three researchers independently evaluated each point for each map tile provider.



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# Results



Map Source	Absolute Error Mean (A/B/C) (m)	Absolute Error Root Mean Squared (A/B/C) (m)	Relative Error Mean (A/B/C) (m)	Relative Error Root Mean Squared (A/B/C) (m)
Google Earth <sup>(9)</sup>	0.74/0.74/0.74	0.89/0.89/0.89	0.57/0.58/0.56	0.73/0.74/0.71
Mapbox <sup>(10)</sup>	0.66/0.66/0.65	0.76/0.76/0.75	0.52/0.50/0.51	0.66/0.66/0.65
Microsoft Azure <sup>(11)</sup>	0.64/0.64/0.64	0.76/0.76/0.76	0.55/0.52/0.54	0.75/0.74/0.76

A = researcher A; B = researcher B; C = researcher C.

Source: FHWA.

# Results



Map Source	Absolute Error Mean (A/B/C) (m)	Absolute Error Root Mean Squared (A/B/C) (m)	Relative Error Mean (A/B/C) (m)	Relative Error Root Mean Squared (A/B/C) (m)
Google Earth <sup>(9)</sup>	0.74/0.74/0.74	0.89/0.89/0.89	0.57/0.58/0.56	0.73/0.74/0.71
Mapbox <sup>(10)</sup>	0.66/0.66/0.65	0.76/0.76/0.75	0.52/0.50/0.51	0.66/0.66/0.65
Microsoft Azure <sup>(11)</sup>	0.64/0.64/0.64	0.76/0.76/0.76	0.55/0.52/0.54	0.75/0.74/0.76

A = researcher A; B = researcher B; C = researcher C.

Source: FHWA.

However, only Google Earth displayed all feature points



# MAP Versus RGA Message

- ▶ MAP is J2735, while RGA is J2945/A.<sup>(2,4)</sup>
- ▶ MAP contains intersection and road geometry data (optional).
- ▶ RGA contains road geometry attributes such as base layer, geometry container, movement container, wayuse container, and controlled-intersections container.
- ▶ RGA provides additional road information beyond MAP.
- ▶ RGA uses a few variables from MAP.

# Next Steps



- ▶ Make the final release of the MAP tool with the open-source compiler.<sup>(1)</sup>
- ▶ Review existing documentation for J2945/A and guidance from the Connected Vehicle Pooled Fund Study.<sup>(4,14)</sup>
- ▶ Consider and evaluate proposed alternatives for the base map.



# Questions?

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